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(54) Apparatus and method for positioning of a GPS receiver

Gerät und Verfahren zum Positionieren eines GPS-Empfängers

Appareil et méthode de positionnement d'un récepteur GPS

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Description

BACKGROUND OF THE INVENTION

1. Field of the invention

This invention relates to a method and apparatus for positioning and, more particularly, to a method and GPS (Global Positioning System) receiver for positioning on the Globe by making use of satellite signals transmitted from a plurality of artificial satellites.

2. Description of the Prior Art

One of the positioning systems currently in service utilizing artificial satellites is known as a so-called Global Positioning System (GPS). In accordance with this positioning system, the entire surface of the Earth is covered by a total of 24 GPS satellites when all of them are launched in six orbits at approximately 20,200 km above the Earth with four GPS satellites per each. Each GPS satellite transmits a satellite signal containing navigational data through a spread-spectrum transmission system. Positioning may be performed on the ground, on the sea or in the air by receiving satellite signals from a plurality of GPS satellites, for example, by receiving the satellite signals from three GPS satellites for two-dimensional positioning and that from four GPS satellites for three-dimensional positioning. Basing on the navigational data contained in the satellite signal from each GPS satellite, positional information of the receiving point such as a latitude, longitude and altitude can be reckoned in real time.

This Global Positioning System was originally developed for U.S. military use, however, a part of the satellite or GPS signal (C/A code) has been made available for civil use. Therefore, it becomes possible to provide a navigation system for use in motor vehicles, water vessels and aircraft by making use of the satellite signals.

Since the satellite signals are transmitted by the spread-spectrum transmission system, the reception of the satellite signal must be initiated by locking a phased-locked loop (PLL) circuit of the GPS receiver exactly on a receiving frequency of the satellite signal. Upon successful locking of the PLL circuit, the received spread-spectrum signal is despread and demodulated to receive navigation data.

One of the typical motor vehicle-mounted navigation apparatus of the prior art for use in the GPS system is a single-channel type GPS receiver having a single antenna, single RF receiving unit and single signal processing unit. Accordingly, it has been necessary to receive satellite signals from the minimum number of GPS satellites in a sequential manner through the single receiving channel for positioning.

Another type of known motor vehicle-mounted GPS receiver, see for example Proceedings of IEEE, Vol 77, No. 11, November 1989, New York, US ; SCHUCHMAN

ET AL: "Applicability of an Augmented GPS for Navigation in the National Airspace system", pages 1709-1727 is a multi-channel GPS receiver having a plurality of receiving channels each of which is assigned for receiving a satellite signal from an allotted GPS satellite.

In the prior art system, in case of receiving satellite signals transmitted by a plurality of GPS satellites with a single antenna, obstructions such as a building and the like have prevented the GPS receiver from receiving the satellite signals transmitted by the predetermined minimum number of GPS satellites which are needed for positioning. This problem is particularly encountered with the motor vehicle-mounted GPS receiver which moves together with the motor vehicle.

As described, in the typical multi-channel type motor vehicle-mounted GPS receiver of the prior art, the required number of GPS satellites for positioning has been shared with multiple receiving channels for receiving satellite signals transmitted therefrom. However, one of disadvantages of this prior art system is that, if any of the GPS satellites, a satellite signal from which has been received by one of the receiving channels of the GPS receiver, is obstructed by a building or other obstacles, it will become impossible to receive the required satellite signals from the minimum number of GPS satellites for positioning. This results in an interruption of the positioning by the GPS receiver.

It is therefore an object of the present invention to provide a GPS receiver which is capable of maintaining as good receiving condition as possible even if any GPS satellite in use is obstructed by an obstacle in the midst of positioning.

It is another object of the present invention to provide a positioning method for use with a motor vehicle-mounted GPS receiver, wherein the GPS receiver is maintained at high degree of accuracy of positioning even if any GPS satellite in use is obstructed by an obstacle and resulting in no reception of satellite signal therefrom in the midst of positioning.

SUMMARY OF THE INVENTION

In order to achieve the foregoing and other objects of the present invention, as a first embodiment of the invention, there is provided, as set out in the appended claim 1, a single-channel type GPS receiver having a plurality of antennas, an antenna switching device for selecting any of the plurality of antennas, and a controller for controlling the antenna switching device to select any of the plurality of antennas which receives satellite signals from the maximum number of GPS satellites.

In accordance with the first embodiment of the present invention, it is possible to select the best antenna for receiving satellite signals from among the plurality of antennas and to utilize the selected antenna for positioning. Thus the satellite signals from the maximum number of GPS satellites can be received in any case even if any of the GPS satellites is obstructed by a build-

ing or the like to maintain the positioning operation by making use of the rest of GPS satellites in contact.

In accordance with a second embodiment of the present invention, there is provided, as set out in the appended claim 5, a single channel type GPS receiver having a plurality of antennas, an antenna switching device for selecting any of the plurality of antennas, and a control device for selecting a predetermined number of GPS satellites being suited for positioning from among all of GPS satellites in contact with respective antennas when each of the antennas fails to receive satellite signals transmitted by the predetermined minimum number of GPS satellites, and further, controlling the antenna switching device for sequentially selecting the antennas which correspond to the selected GPS satellites.

Further, according to the second embodiment of the invention, if the total number of GPS satellites in contact with the all antennas becomes less than the predetermined minimum number of GPS satellites, the minimum number of GPS satellites required for positioning are selected from among all of GPS satellites the satellite signals of which are received by respective antennas. Therefore, even if the positioning becomes impossible with the satellite signals received by each individual antenna, it is possible to carry out the positioning by utilizing the GPS satellites in contact with the all antennas. The required number of GPS satellites may be determined in such a manner as by selecting a combination of the GPS satellites having the smallest PDOP (Position Dilution of Precision) value or by selecting the GPS satellites in order of signal strength of the received satellite signals.

In accordance with a third embodiment of the present invention, there is provided, as set out in the appended claim 11, a positioning method for use with a multi-channel type motor vehicle-mounted GPS receiver having a plurality of receiving channels each of which includes an antenna, an RF receiving unit and a signal processing unit independently. According to this positioning method, each receiving channel independently receives satellite signals transmitted from the GPS satellites in contact, a predetermined number of GPS satellites which are currently considered to be the most suitable for positioning are selected from among all of GPS satellites whose signals are being received by each receiving channel, and the positioning is performed by making use of navigation data obtained from the selected GPS satellites.

That is, according to the third embodiment of the invention, since the predetermined number of satellites which are currently considered to be the most suitable for positioning are selected from among all of GPS satellites whose transmitted signals are received by all receiving channels and navigation data contained in the transmitted signals are used to carry out the positioning operation, even if any GPS satellite is obstructed by a building or other obstacles in the midst of positioning, a GPS satellite other than the selected ones may be sub-

stituted for the obstructed GPS satellite, and then the positioning can be carried out by making use of navigation data of the newly selected GPS satellite without any intermission. The selection of the GPS satellites which are considered to be the most suitable for positioning at a given point of time may be performed in view of the PDOP value. That is, the selection may easily be done by only selecting a combination of the GPS satellites which has the smallest PDOP value.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram showing a motor vehicle-mounted GPS receiver embodying the present invention;

Fig. 2 is a diagram showing antennas to be used in the embodiment of Fig. 1;

Fig. 3 is a flowchart showing operational steps performed by the embodiment of Fig. 1;

Fig. 4 is a flowchart showing operational steps performed by another embodiment of this invention;

Fig. 5 is a block diagram showing another motor vehicle-mounted GPS receiver embodying the present invention; and

Fig. 6 is a diagram showing GPS satellites whose signals are received by respective channels of the GPS receiver of Fig. 5.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

Preferred embodiments of the present invention will now be described with reference to the accompanying drawings.

Fig. 1 is a block diagram showing a first embodiment of this invention taking the form of a motor vehicle-mounted GPS receiver. In Fig. 1, elements 1A and 1B denote two antennas mounted independently of each other, a block 2 denotes an antenna switching unit for selecting any of the two antennas as needed, a block 3 denotes an RF receiving unit for receiving satellite signals sequentially from target GPS satellites by despread the received satellite signals, a block 4 denotes a signal processing unit for reckoning the current position based on the navigation data contained in the received satellite signals of the GPS satellites, and a block 5 denotes a control unit for controlling the above components. As shown in Fig. 2, the two antennas 1A and 1B should preferably be mounted apart from each other to the full extent as possible, for example, at the front side and the rear side of the motor vehicle.

The first embodiment of the invention will now be described with reference to a flowchart of Fig. 3. Upon initiation of the apparatus, the GPS receiver performs a first step S31 of receiving a satellite signal transmitted by the GPS satellite in contact. At steps S32 and S33, the controller 5 controls the antenna switching unit 2 to alternately select the antennas 1A and 1B, sends satel-

lite signals received by respective antennas to the RF receiving unit 3 and signal processing unit 4 and then decides a number of GPS satellites for each of the antennas 1A and 1B. At step S34, The controller 5 compares the number of GPS satellites in contact with the antennas 1A and 1B for deciding which antenna excels in number of contacts with the GPS satellites.

If the antenna 1A is decided at step S35 to be greater in the number of contacted GPS satellites than that of the antenna 1B, the controller 5 switches the antenna switching unit 2 to select the antenna 1A in order to receive the satellite signals through the antenna 1A. While, if the antenna 1B is found to be greater in the number of contacted GPS satellites, the controller 5 switches the antenna switching unit 2 to select the antenna 1B in order to receive the satellite signals through the antenna 1B at step S36.

The controller 5 repeats the aforesaid operational steps at predetermined intervals. Consequently, either of the antennas 1A and 1B which can receive satellite signals from greater number of GPS satellites is used for receiving the transmissions from the GPS satellites. If any of the GPS satellites in contact is obstructed by an obstacle such as a building, it is still possible to continue the positioning by utilizing the rest of GPS satellites which are still in contact.

Fig. 4 is a flowchart showing operational steps to be performed by a second embodiment of the invention. The second embodiment of this invention has the same construction as that of the first embodiment. In accordance with the second embodiment of this invention, the minimum number of GPS satellites which is considered to be a threshold value for positioning, for example, five GPS satellites, are assigned preliminarily for each of the two antennas 1A and 1B and are utilized in decision steps following the step S44 in the flowchart of Fig. 4.

Upon initiation of the GPS receiver, the GPS receiver perform a first step S41 of receiving satellite signals from GPS satellites in contact. At steps S42 and S43, the control unit 5 controls the antenna switching unit 2 for finding the number of GPS satellites that can be readable with respective antennas by selecting the antennas 1A and 1B alternately and supplying received satellite signals to the RF receiving unit 3 and signal processing unit 4. The control unit 5 determines at step S44 whether or not the number of GPS satellites in contact with each of the antennas 1A and 1B exceeds the minimum number of GPS satellites preliminarily determined therefor.

If the number of GPS satellites in contact exceeds the predetermined minimum number of GPS satellites either with the antenna 1A or antenna 1B, the program goes to step S45 for deciding which antenna has greater number of GPS satellites in contact than the other. The reception of satellite signals is then performed either at step S46 or S47 by utilizing the antenna having the greater number of GPS satellites in contact.

If it is found at step S44 that the number of GPS

satellites in contact with the both antennas 1A and 1B does not exceed the predetermined minimum number of GPS satellites, the program then goes to step S48 and it is determined whether or not the both antennas 1A and 1B are less than the predetermined minimum number of GPS satellites in contact. If it has not, the program goes to step S49 for determining which antenna is less than the predetermined minimum number of GPS satellites in contact. The reception of satellite signals is then performed either at step S50 or S51 by utilizing the antenna which is not less than the predetermined minimum number of GPS satellites in contact. However, if it has, the program goes to S52 and the minimum required number of GPS satellites for positioning at that point of time are selected from among all of GPS satellites in contact with the both antennas 1A and 1B.

As described, one of the typical selecting conditions for GPS satellites at step S52 is to select a combination of the required number of GPS satellites having the smallest PDOP value and that another condition is to select the required number of GPS satellites in order of signal strength of the received satellite signals.

Upon selecting the required number of satellites at step S52, the controller 5 adaptively controls the antenna switching unit 2 for sequentially receiving satellite signals from the selected plurality of GPS satellites by utilizing the both antennas 1A and 1B.

The controller 5 repeats the above described operational steps at predetermined intervals. Consequently, if both of the two antennas 1A and 1B become a state of being in contact with less than the predetermined minimum number of GPS satellites, the required minimum number of GPS satellites suited for positioning are selected from among all of GPS satellites in contact with the both antennas 1A and 1B. Accordingly, if any GPS satellite whose transmissions are being received is obstructed by a building or the like, it is possible to perform the positioning by making use of another GPS satellite in contact without interrupting the positioning operation.

Two antennas are employed in the foregoing preferred embodiments of the invention, however, it is apparent for those skilled in the art that more than two antennas may be employed to receive transmissions from the GPS satellites. Further, the minimum number of GPS satellites to be used at the decision steps in the second embodiment may be determined independently for each of the antennas in use or may be determined to be the same for all antennas. It depends on a system specification to be employed for positioning whichever the minimum number of GPS satellites is determined for all antenna.

Still another embodiment of the present invention will now be described with reference to Figs. 5 and 6. Fig. 5 is a block diagram of a motor vehicle-mounted GPS receiver embodying the present invention. According to this preferred embodiment, a GPS receiver having three receiving channels is employed for positioning and thereby first, second and third channels are denoted re-

spectively by #1 ch, #2 ch and #3 ch, and that their corresponding components are designated by reference numerals suffixed by A, B and C, respectively, like an antenna 1A for the antenna which belongs to the receiving channel #1 ch.

In Fig. 5, three antennas 1A, 1B and 1C are mounted independently of one another, RF receiving units 2A, 2B and 2C receive satellite signals by despread the satellite signals from GPS satellites received through respective antennas, signal processing units 3A, 3B and 3C decode the satellite signals received by the RF receiving units 2A, 2B and 2C into original digital data, and a control unit 4 selects a predetermined number, such as four, of GPS satellites considered to be the most suitable for positioning at that point of time and calculates the current position by utilizing the navigation data contained in the satellite signals from the selected GPS satellites. The three antennas 1A, 1B and 1C should preferably be mounted at separated positions such as inside of the windshield, inside of the rear window or other appropriate positions.

Upon initiation of the reception of satellite signals, the GPS satellite transmissions received by the antenna 1A, 1B and 1C are despread at the RF receiving units 2A, 2B and 2C, respectively, for receiving satellite signals transmitted as many GPS satellites as possible by each of the receiving channels. The received satellite signals are then fed to the control unit 4 after decoding them into the original digital data by the signal processing units 3A, 3B and 3C.

It is assumed that the receiving channels are all in the receiving status as shown in Fig. 6(A), Fig. 6(B) and Fig. 6(C), that is, if satellite signals from the three GPS satellites S1, S3 and S4 are received by the receiving channel #1 ch, satellite signals from the three satellites S2, S3 and S7 are received by the receiving channel #2 ch, and satellite signals from the two satellites S5 and S6 are received by the receiving channel #3 ch, the signal processing units 3A, 3B and 3C decode each of the satellite signals received by the respective receiving channels and in turn the decoded signals are fed to the control unit 4.

The control unit 4 selects a combination of the GPS satellites that has the minimum PDOP value, for example, the GPS satellites S1, S2, S3 and S6 identified by open circle (○) in Fig. 6, by utilizing the navigation data received from the GPS satellites S1 - S7 being fed by the signal processing units 3A, 3B and 3C, and thereby the present position of the vehicle which carries the GPS receiver is computed by the control unit 4 by making use of the navigation data of these selected GPS satellites. This allows the GPS receiver to perform the positioning operation with high degree of accuracy at that point of time. In the example of Fig. 6, regarding the GPS satellite S3, satellite signals from which are received by the two receiving channels #1 ch and #2 ch. In this case, it is preferable to perform the positioning by utilizing the receiving channel whichever the received signal

strength is stronger.

The positioning data thus obtained is transmitted to a navigation apparatus (not shown) for displaying, as positional information, on a cathode-ray tube (CRT) or the like on which a map is displayed.

Further, If the GPS satellite S2 is obstructed by a building or other obstacles in the midst of above-described positioning operation and becomes no reception of satellite signal therefrom, the control unit 4 eliminates the obstructed satellite S2 and immediately recalculates the PDOP values using the remaining six GPS satellites in contact for selecting another combination of four GPS satellites that has the minimum PDOP value at that point of time, and then the positioning is continued by utilizing the navigation data of the newly selected four GPS satellites. Accordingly, even if several GPS satellites are obstructed by a building or the like for causing no reception of satellite signals, it is possible to perform the positioning without interruption by selecting the best combination of the GPS satellites available for high degree of accuracy of positioning from among the rest of GPS satellites in contact.

The third preferred embodiment has been described with reference to a three-channel type GPS receiver, however, the positioning method according to this invention is not to be considered to be limited thereto, the invention may also be applied for use with other type of GPS receivers having two or more receiving channels.

As it has been described above, according to the first aspect of the invention, a single antenna of the best in the number of contact with GPS satellites is selected from a plurality of antennas in order to receive satellite signals, while, according to the second and third aspects of the invention, the required minimum number of GPS satellites considered to be the best of combination in view of PDOP value for positioning are selected from among all of GPS satellites being in contact with each antenna or all antennas. This invention allows the uninterrupted positioning operation for the GPS receiver to perform by substituting the rest of GPS satellites in contact for the obstructed GPS satellite even if some satellite is obstructed by a building or other obstacles for causing no reception of satellite signals. This invention is particularly effective when implemented in a motor vehicle-mounted GPS receiver for giving high degree of accuracy of positioning regardless of the change of status of satellite signal reception.

While the invention has been described with reference to preferred embodiments, it will be understood by those skilled in the art that various changes may be made and equivalents may be substituted for elements thereof without departing from the scope of the invention.

Claims

1. A single receiving channel GPS receiver comprising:
a plurality of antennas (1A, 1B); antenna switching means (2) for selecting any of said plurality of antennas (1A, 1B) by switching; and control means (5), characterized in that the control means (5) is adapted to control said antenna switching means (2) at predetermined time intervals to sequentially select each antenna of said plurality of antennas (1A, 1B) for finding the number of GPS-satellites in contact with each antenna and subsequently within said predetermined time interval to control said antenna switching means (2) to select that antenna among said plurality of antennas (1A, 1B) which has the maximum number of GPS-satellites in contact. 5
2. Receiver according to claim 1, **characterized in that** said said plurality of antennas (1A, 1B) are two antennas mounted at the front end (1A) and the rear end (1B) of a motor vehicle. 10
3. Receiver according to claim 1, **characterized in that** said control means (5) compares numbers of satellites in contact with said plurality of antennas (1A, 1B). 15
4. Receiver according to claim 1, **characterized by** a RF signal receiving means (3) for receiving navigation data sequentially from the GPS satellites by despreading received satellite signals; and processing means (4) for reckoning a current position by making use of the navigation data. 20
5. A single receiving channel GPS receiver comprising:
a plurality of antennas (1A, 1B); antenna switching means (2) for selecting any of said plurality of antennas by switching; and control means (5), characterized in that the control means (5) is adapted to control said antenna switching means at predetermined time intervals to sequentially select each antenna of said plurality of antennas (1A, 1B) for finding the number of GPS-satellites in contact with each antenna and, when each of said plurality of antennas (1A, 1B) fails to receive satellite signals from a predetermined minimum number of GPS-satellites, to select a required number of GPS-satellites considered to be the most suitable for positioning from among all of GPS satellites in contact with said plurality of antennas (1A, 1B) and subsequently within said predetermined time intervals to control said antenna switching means (2) to select the satellites so selected in a sequential manner. 25
6. Receiver according to claim 5, **characterized by** a RF signal receiving means (3) for receiving navigation data sequentially from the GPS satellites by despreading received satellite signals; and by a processing means (4) for reckoning a current position by making use of the navigation data. 30
7. Receiver according to claim 5, **characterized in that** said required number of GPS satellites is determined by selecting a combination of GPS satellites in contact having the smallest PDOP value. 35
8. Receiver according to claim 5, **characterized in that** said required number of GPS satellites is selected in order of signal strength of the received satellite signals. 40
9. Receiver according to claim 5, **characterized in that** said predetermined minimum number of GPS satellites is determined independently for each of the plurality of antennas (1A, 1B). 45
10. Receiver according to claim 5, **characterized in that** said predetermined minimum number of GPS satellites is determined to be the same for each of the plurality of antennas (1A, 1B). 50
11. A positioning method for use with a vehicle-mounted GPS receiver having a plurality of receiving channels (#1ch, #2ch, #3ch) each of which includes an antenna (1A, 1B, 1C), an RF receiving unit (2A, 2B, 2C) and a signal processing unit (3A, 3B, 3C), characterized by the steps of: receiving, independently through each of said receiving channels (#1ch, #2ch, #3ch), satellite signals from as many GPS-satellites as possible; selecting a predetermined number of GPS satellites considered to be the most suitable for positioning at the current point of time from among all of GPS satellites in contact with respective receiving channels (#1ch, #2ch, #3ch), and performing the positioning by making use of navigation data obtained from said selected GPS satellites. 55
12. A Method according to claim 11, **characterized in that** said step of selecting selects a predetermined number of GPS satellites considered to be the best of combinations in view of PDOP value for positioning.
13. A method according to claim 12, **characterized in that** said step of selecting is performed when any of the selected GPS satellites is obstructed by an obstacle.

Patentansprüche

1. GPS-Empfänger mit einem einzigen Empfangskanal, umfassend: eine Mehrzahl von Antennen (1A, 1B); eine Antennenumschalteneinrichtung (2) zum Auswählen einer der Mehrzahl von Antennen (1A, 1B) durch Umschalten, und eine Steuereinrichtung (5), dadurch gekennzeichnet, daß die Steuereinrichtung (5) dazu ausgelegt ist, die Antennenumschalteneinrichtung (2) zu vorbestimmten Zeitintervallen umzuschalten, um jede Antenne der Mehrzahl von Antennen (1A, 1B) sequentiell zum Auffinden der Anzahl von GPS-Satelliten auszuwählen, die sich in Kontakt mit jeder Antenne befinden, und um daraufhin innerhalb des vorbestimmten Zeitintervalls die Antennenumschalteneinrichtung (2) so zu steuern, daß diejenige Antenne unter der Mehrzahl von Antennen (1A, 1B) ausgewählt wird, die die Maximalanzahl an kontaktierten GPS-Satelliten aufweist. 5 10 15 20
2. Empfänger nach Anspruch 1, dadurch gekennzeichnet, daß die Mehrzahl von Antennen (1A, 1B) zwei Antennen sind, die am vorderen Ende (1A) und am rückwärtigen Ende (1B) eines Motorfahrzeugs angebracht sind. 25
3. Empfänger nach Anspruch 1, dadurch gekennzeichnet, daß die Steuereinrichtung (5) die Anzahlen von sich in Kontakt mit der Mehrzahl von Antennen (1A, 1B) befindlichen Satelliten vergleicht. 30
4. Empfänger nach Anspruch 1, gekennzeichnet durch eine RF-Signalempfangseinrichtung (3) zum Empfangen von Navigationsdaten sequentiell von den GPS-Satelliten durch Entfalten empfangener Satellitensignale, und eine Verarbeitungseinrichtung (4) zum Errechnen einer aktuellen Position unter Verwendung der Navigationsdaten. 35 40
5. GPS-Empfänger mit einem einzigen Empfangskanal, umfassend: eine Mehrzahl von Antennen (1A, 1B); eine Antennenumschalteneinrichtung (2) zum Auswählen einer der Mehrzahl von Antennen durch Umschalten, und eine Steuereinrichtung (5), dadurch gekennzeichnet, daß die Steuereinrichtung (5) dazu ausgelegt ist, die Antennenumschalteneinrichtung (2) zu vorbestimmten Zeitintervallen so zu steuern, daß jede Antenne der Mehrzahl von Antennen (1A, 1B) zum Auffinden der Anzahl von GPS-Satelliten, die sich in Kontakt mit jeder Antenne befinden, sequentiell auszuwählen, und, wenn jede der Mehrzahl von Antennen (1A, 1B) nicht in der Lage ist, Satellitensignale von einer vorbestimmten Minimalanzahl von GPS-Satelliten zu empfangen, eine vorbestimmte Anzahl von GPS-Satelliten auszuwählen, die als am geeignetsten zur Positionierung unter sämtlichen GPS-Satelliten 45 50 55
- erachtet werden, die sich in Kontakt mit der Mehrzahl von Antennen (1A, 1B) befinden, und um daraufhin innerhalb der vorbestimmten Zeitintervalle die Antennenumschalteneinrichtung (2) so zu steuern, daß die derart ausgewählten Satelliten in sequentieller Weise ausgewählt werden.
6. Empfänger nach Anspruch 5, gekennzeichnet durch eine RF-Signalempfangseinrichtung (3) zum Empfangen von Navigationsdaten sequentiell von den GPS-Satelliten durch Entfalten empfangener Satellitensignale, und eine Verarbeitungseinrichtung (4) zum Errechnen einer aktuellen Position unter Verwendung der Navigationsdaten.
7. Empfänger nach Anspruch 5, dadurch gekennzeichnet, daß die erforderliche Anzahl an GPS-Satelliten durch Auswählen einer Kombination von kontaktierten GPS-Satelliten ermittelt wird, die den kleinsten PDOP-Wert aufweisen.
8. Empfänger nach Anspruch 5, dadurch gekennzeichnet, daß die erforderliche Anzahl an GPS-Satelliten in der Rangfolge der Signalstärke der empfangenen Satellitensignale ausgewählt wird.
9. Empfänger nach Anspruch 5, dadurch gekennzeichnet, daß die vorbestimmte Minimalanzahl an GPS-Satelliten unabhängig für jede der Mehrzahl von Antennen (1A, 1B) ermittelt wird.
10. Empfänger nach Anspruch 5, dadurch gekennzeichnet, daß die vorbestimmte Minimalanzahl an GPS-Satelliten für jede der Mehrzahl von Antennen (1A, 1B) als dieselbe ermittelt wird.
11. Positionierungsverfahren zur Verwendung mit einem an einem Fahrzeug angebrachten GPS-Empfänger mit einer Mehrzahl von Empfangskanälen (#1ch, #2ch, #3ch), von denen jeder eine Antenne (1A, 1B, 1C) aufweist, eine RF-Empfangseinheit (2A, 2B, 2C) und eine Signalverarbeitungseinheit (3A, 3B, 3C), gekennzeichnet durch die Schritte: Unabhängiges Empfangen von Satellitensignalen von so vielen GPS-Satelliten wie möglich durch jeden der Empfangskanäle (#1ch, #2ch, #3ch); Auswählen einer vorbestimmten Anzahl von GPS-Satelliten, die am geeignetsten für eine Positionierung zum aktuellen Zeitpunkt erachtet werden, aus sämtlichen GPS-Satelliten, die in Kontakt mit jeweiligen Empfangskanälen (#1ch, #2ch, #3ch) stehen, und Durchführen der Positionierung durch Verwenden von Navigationsdaten, die von den ausgewählten GPS-Satelliten erhalten werden.
12. Verfahren nach Anspruch 11, dadurch gekennzeichnet, daß der Auswahlschritt eine vorbestimmte Anzahl von GPS-Satelliten auswählt, die als be-

ste Kombination im Hinblick auf den PDOP-Wert zur Positionierung erachtet werden.

13. Verfahren nach Anspruch 12, dadurch gekennzeichnet, daß der Auswahlschritt durchgeführt wird, wenn irgendeiner der ausgewählten GPS-Satelliten durch ein Hindernis verdeckt wird. 5

Revendications 10

1. Récepteur GPS à canal de réception unique comprenant : une pluralité d'antennes (1A,1B) ; des moyens de commutation d'antenne (2) pour la sélection d'une quelconque de ladite pluralité d'antennes (1A,1B) par commutation ; et des moyens de commande (5) ; caractérisé en ce que les moyens de commande (5) sont prévus pour commander lesdits moyens de commutation d'antenne (2), à intervalles de temps prédéterminés, de manière à choisir séquentiellement chaque antenne de ladite pluralité d'antennes (1A,1B) afin de trouver le nombre de satellites GPS en contact avec chaque antenne et ensuite, à l'intérieur dudit intervalle de temps prédéterminé, pour commander lesdits moyens de commutation d'antenne (2) de manière à sélectionner l'antenne, parmi ladite pluralité d'antennes (1A, 1B), qui a le nombre maximal de satellites GPS en contact. 15
2. Récepteur suivant la revendication 1, caractérisé en ce que ladite pluralité d'antennes (1A,1B) comprend deux antennes montées à l'extrémité avant (1A) et à l'extrémité arrière (1B) d'un véhicule automobile. 20
3. Récepteur suivant la revendication 1, caractérisé en ce que lesdits moyens de commande (5) comparent les nombres de satellites en contact avec ladite pluralité d'antennes (1A,1B). 25
4. Récepteur suivant la revendication 1, caractérisé en ce qu'il comprend des moyens de réception, de signal de radiofréquence (3) pour recevoir des données de navigation séquentiellement en provenance des satellites GPS, par resserrement des signaux de satellite reçus ; et des moyens de traitement (4) pour calculer une position en cours, par utilisation des données de navigation. 30
5. Récepteur GPS à canal de réception unique comprenant : une pluralité d'antennes (1A,1B) ; des moyens de commutation d'antenne (2) pour la sélection d'une quelconque de ladite pluralité d'antennes par commutation ; et des moyens de commande (5) ; caractérisé en ce que les moyens de commande (5) sont prévus pour commander lesdits moyens de commutation d'antenne, à intervalles de 35

temps prédéterminés, de manière à sélectionner séquentiellement chaque antenne de ladite pluralité d'antennes (1A,1B) afin de trouver le nombre de satellites GPS en contact avec chaque antenne et, lorsque chacune de ladite pluralité d'antennes (1A, 1B) ne peut pas recevoir des signaux de satellite provenant d'un nombre minimal prédéterminé de satellites GPS, à sélectionner un nombre requis de satellites GPS considérés comme convenant le mieux pour le positionnement parmi tous les satellites GPS en contact avec ladite pluralité d'antennes (1A,1B), et ensuite, à l'intérieur desdits intervalles de temps prédéterminés, pour commander lesdits moyens de commutation d'antenne (2) de manière à sélectionner les satellites ainsi choisis, d'une manière séquentielle. 40

6. Récepteur suivant la revendication 5, caractérisé en ce qu'il comprend des moyens de réception de signal de radiofréquence (3) pour recevoir des données de navigation séquentiellement en provenance des satellites GPS, par resserrement des signaux de satellite reçus ; et des moyens de traitement (4) pour calculer une position en cours par utilisation des données de navigation. 45
7. Récepteur suivant la revendication 5, caractérisé en ce que ledit nombre requis de satellites GPS est déterminé par sélection d'une combinaison de satellites GPS en contact qui a la plus petite valeur PDOP. 50
8. Récepteur suivant la revendication 5, caractérisé en ce que ledit nombre requis de satellites GPS est choisi dans l'ordre de l'intensité de signal des signaux de satellite reçus. 55
9. Récepteur suivant la revendication 5, caractérisé en ce que ledit nombre minimal prédéterminé de satellites GPS est déterminé indépendamment pour chacune de la pluralité d'antennes (1A,1B).
10. Récepteur suivant la revendication 5, caractérisé en ce que ledit nombre minimal prédéterminé de satellites GPS est déterminé à une même valeur pour chacune de la pluralité d'antennes (1A,1B).
11. Méthode de positionnement utilisable avec un récepteur GPS monté sur un véhicule et comprenant une pluralité de canaux de réception (canal N°1, canal N°2, canal N°3) dont chacun comporte une antenne (1A,1B,1C), une unité de réception de radiofréquence (2A,2B,2C) et une unité de traitement de signal (3A,3B,3C), caractérisée par les étapes de : réception, indépendamment par l'intermédiaire de chacun desdits canaux de réception (canal N°1, canal N°2, canal N°3), de signaux de satellite provenant d'un nombre aussi grand que possible de

satellites GPS, sélection d'un nombre prédéterminé de satellites GPS considérés comme convenant le mieux pour le positionnement à l'instant présent parmi tous les satellites GPS en contact avec les canaux de réception respectifs (canal N°1, canal N°2, canal N°3) et exécution du positionnement par utilisation des données de navigation fournies par lesdits satellites GPS choisis.

12. Méthode suivant la revendication 11, caractérisée en ce que ladite étape de sélection choisit un nombre prédéterminé de satellites GPS considérés comme formant la meilleure des combinaisons, sur la base de la valeur PDOP, pour le positionnement.

13. Méthode suivant la revendication 12, caractérisée en ce que ladite étape de sélection est effectuée lorsqu'un quelconque des satellites GPS choisis est occulté par un obstacle.

FIG. 1

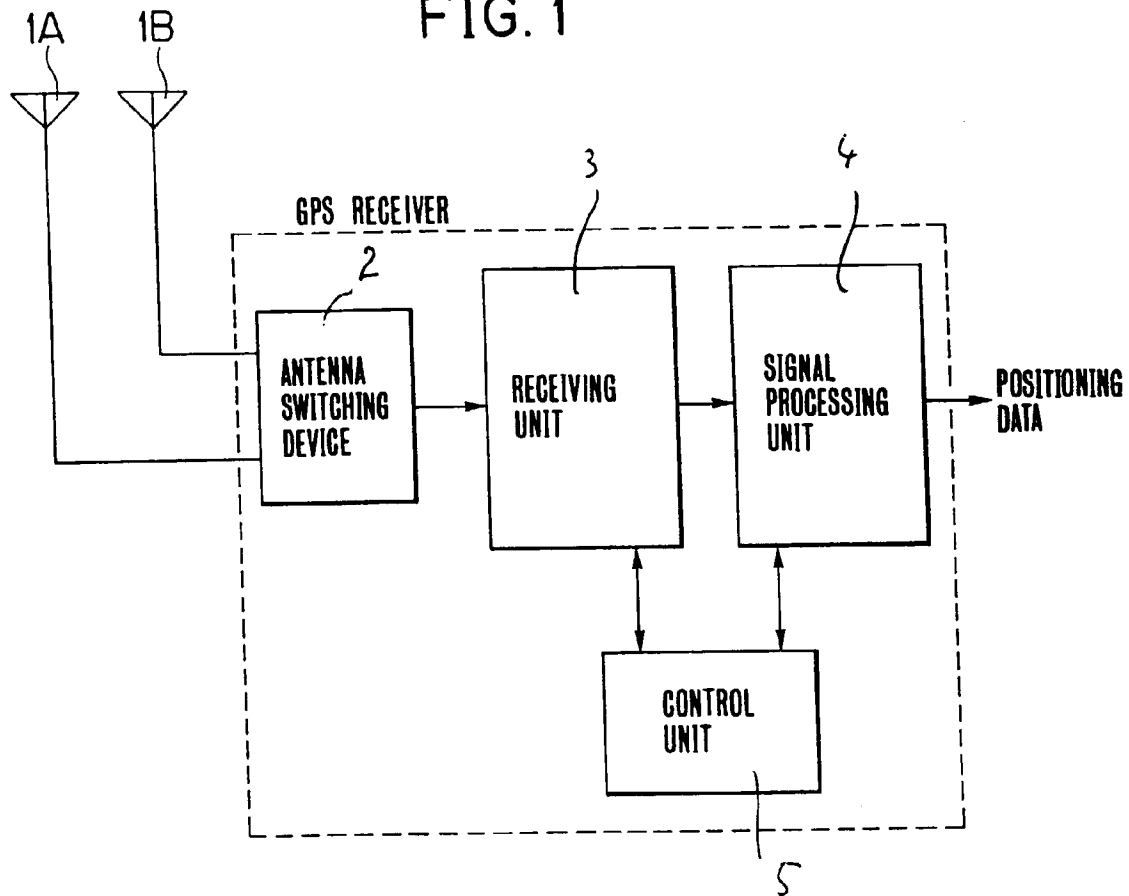


FIG. 2

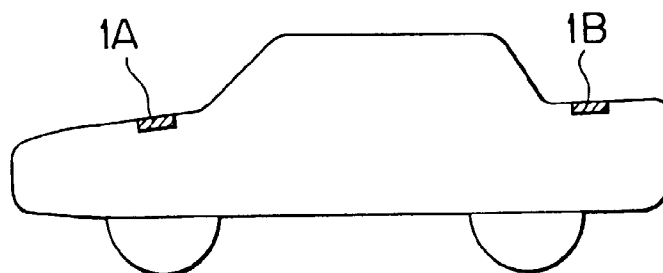


FIG. 3

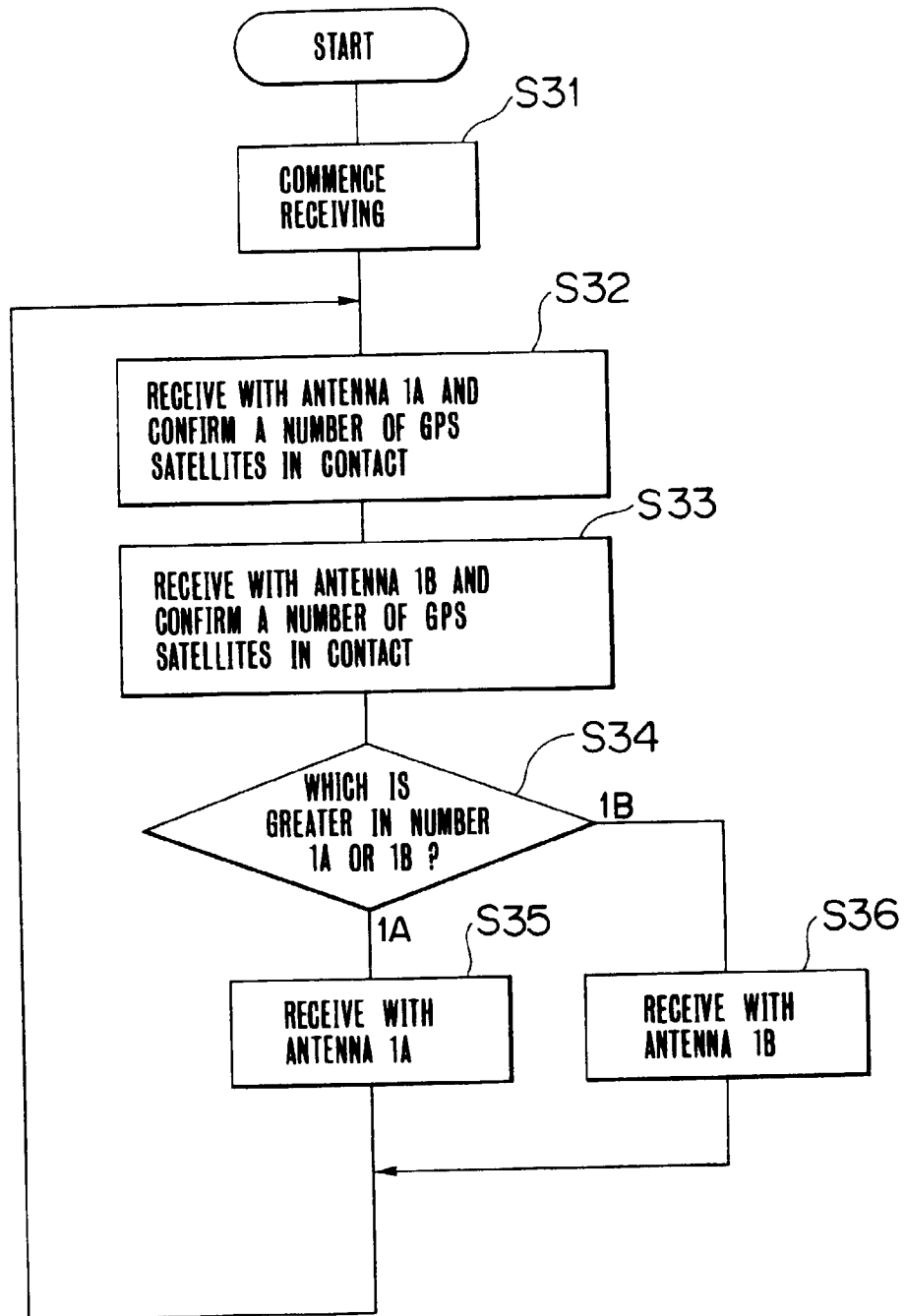


FIG. 4

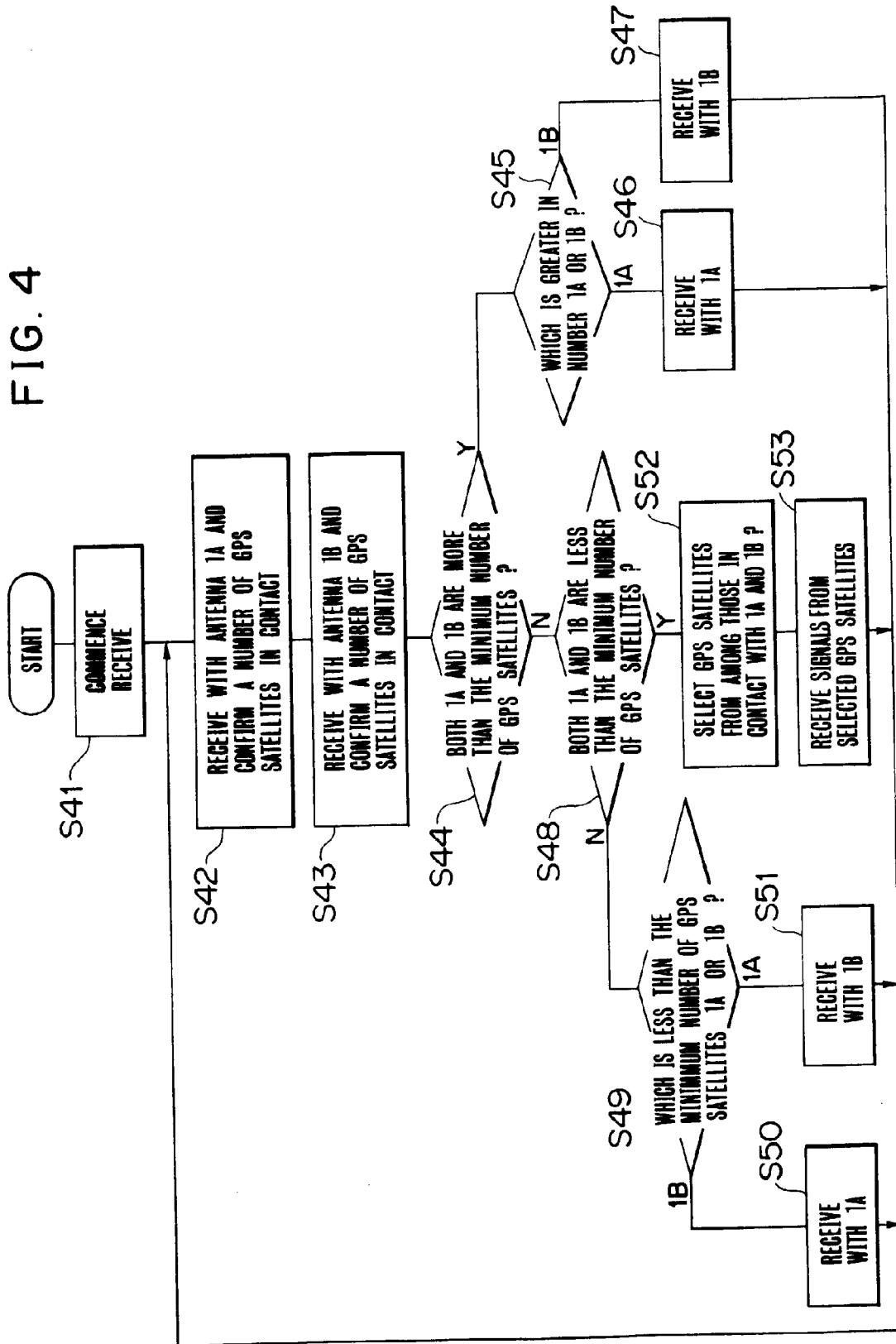


FIG. 5

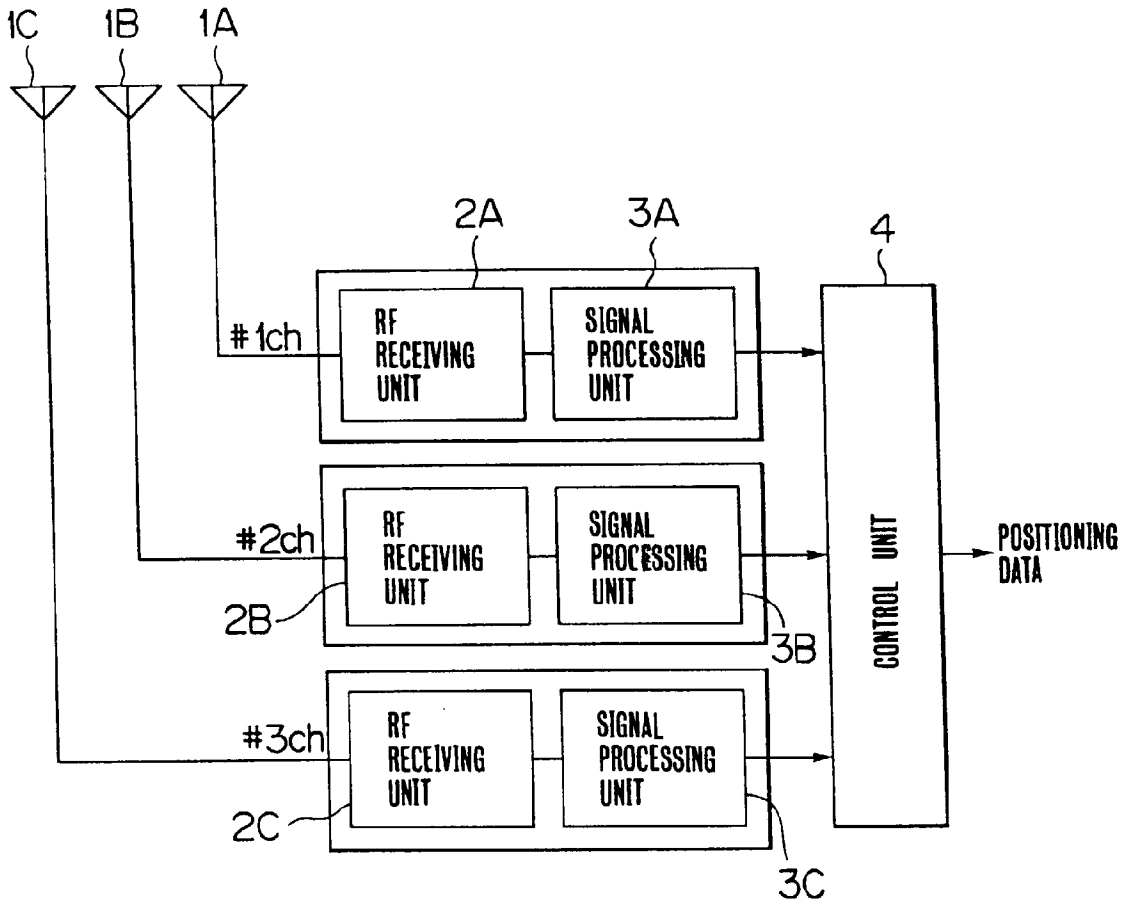


FIG. 6

